

XNAS: Neural Architecture Search with Expert Advice

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DAMO academy

Discovery, Adventure, Momentum and Outlook

MIIL

Israel Machine Intelligence Lab

Machine Intelligence

- 壹 Speech Lab
- 貳 Vision Lab
- 叁 Language Technology Lab
- 肆 Decision Intelligence Lab
- 伍 City Brain Lab

The Alibaba Damo machine intelligence is devoted to research and application in cutting-edge machine intelligence, provides the...

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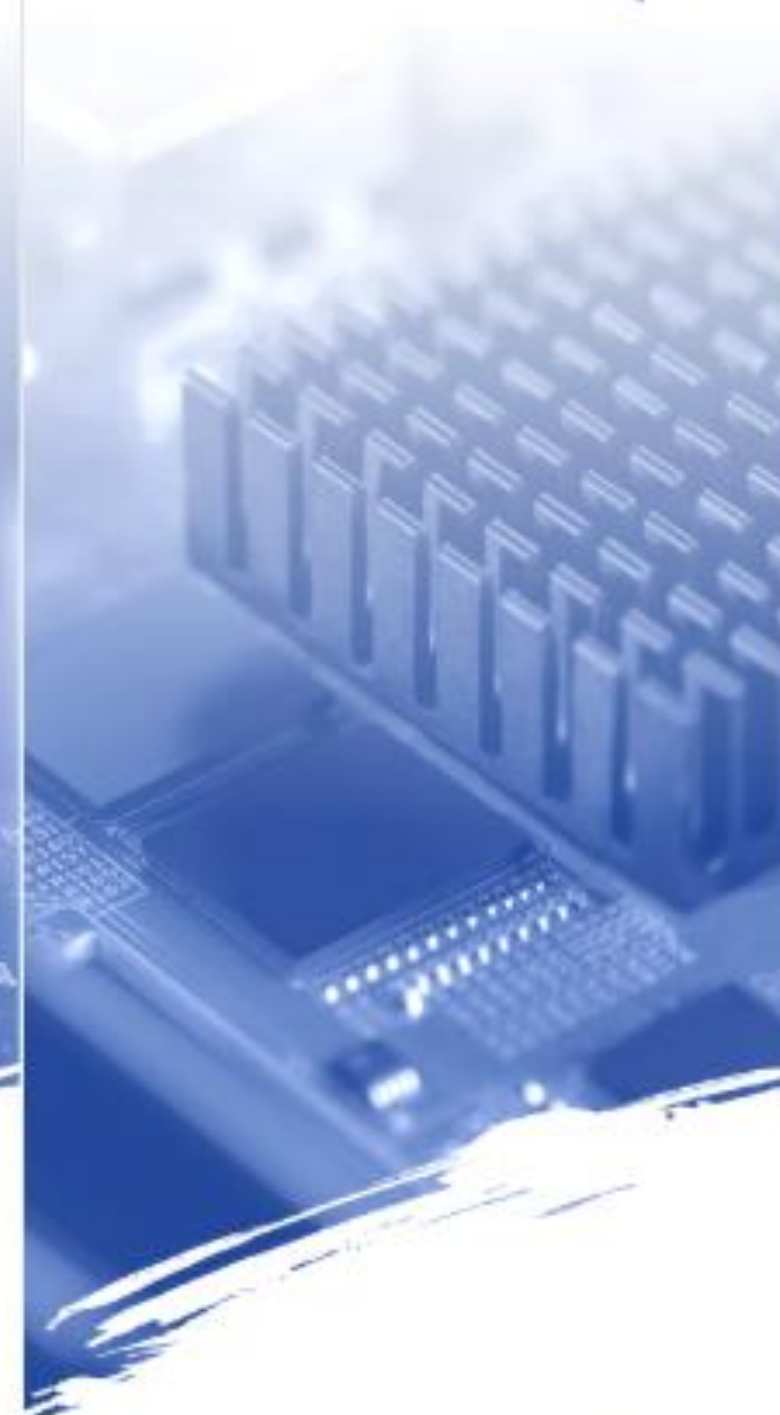
DAMO
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AI is still beyond reach to most companies & people

Even tech-giants are struggling to answer the need in new fields

AI Experts are busy tuning parameters

AutoML::Classification

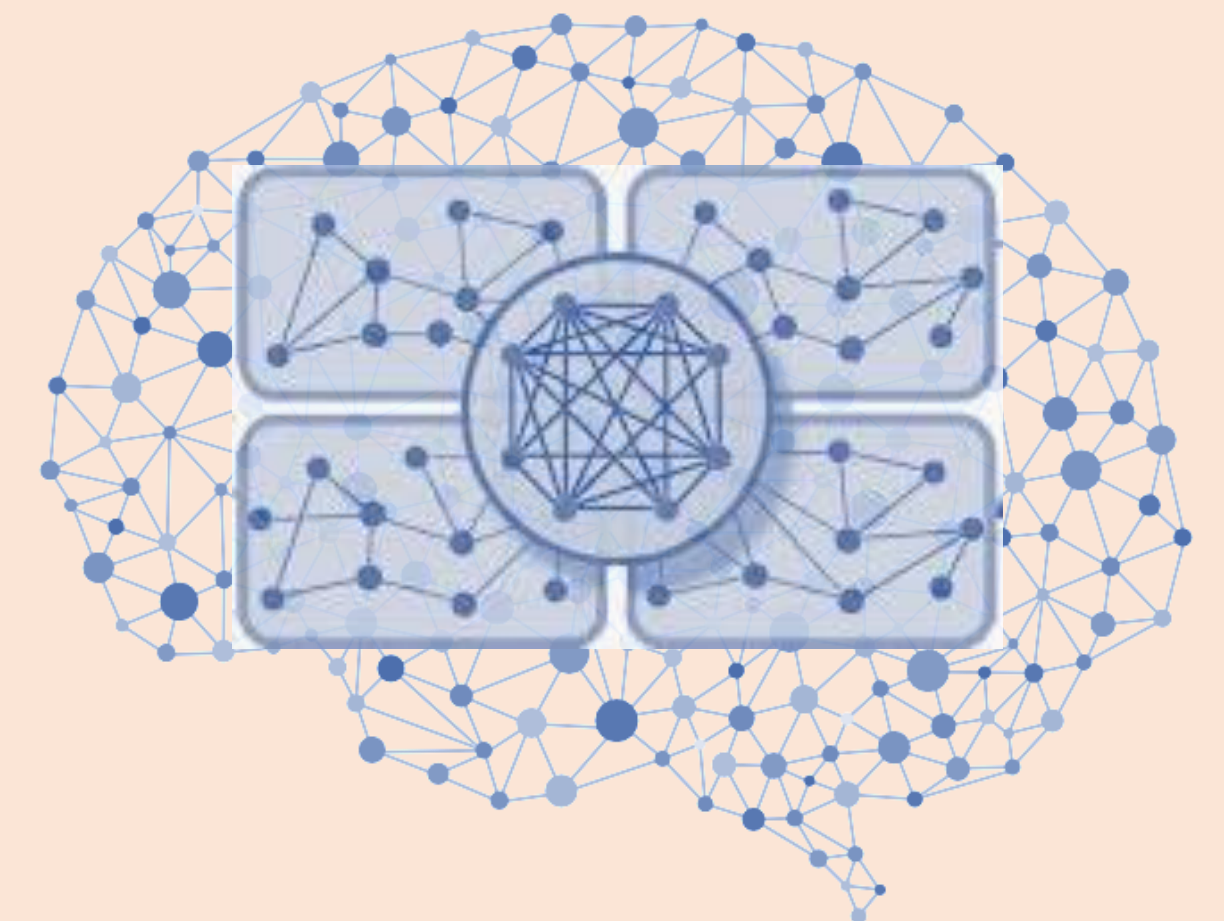


NAS Overview

- The success of deep learning in perceptual tasks is largely due to its automation of the feature engineering process
- This success led to a rising demand for architecture engineering
- NAS, architecture engineering automation, is a logical next step in the mission of fully automating machine learning

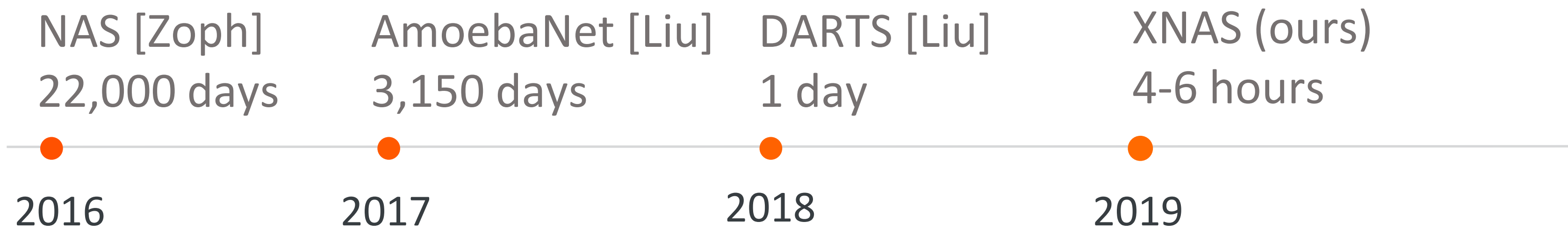
NAS

Automatic **N**eural
Architecture **S**earch



NAS Overview

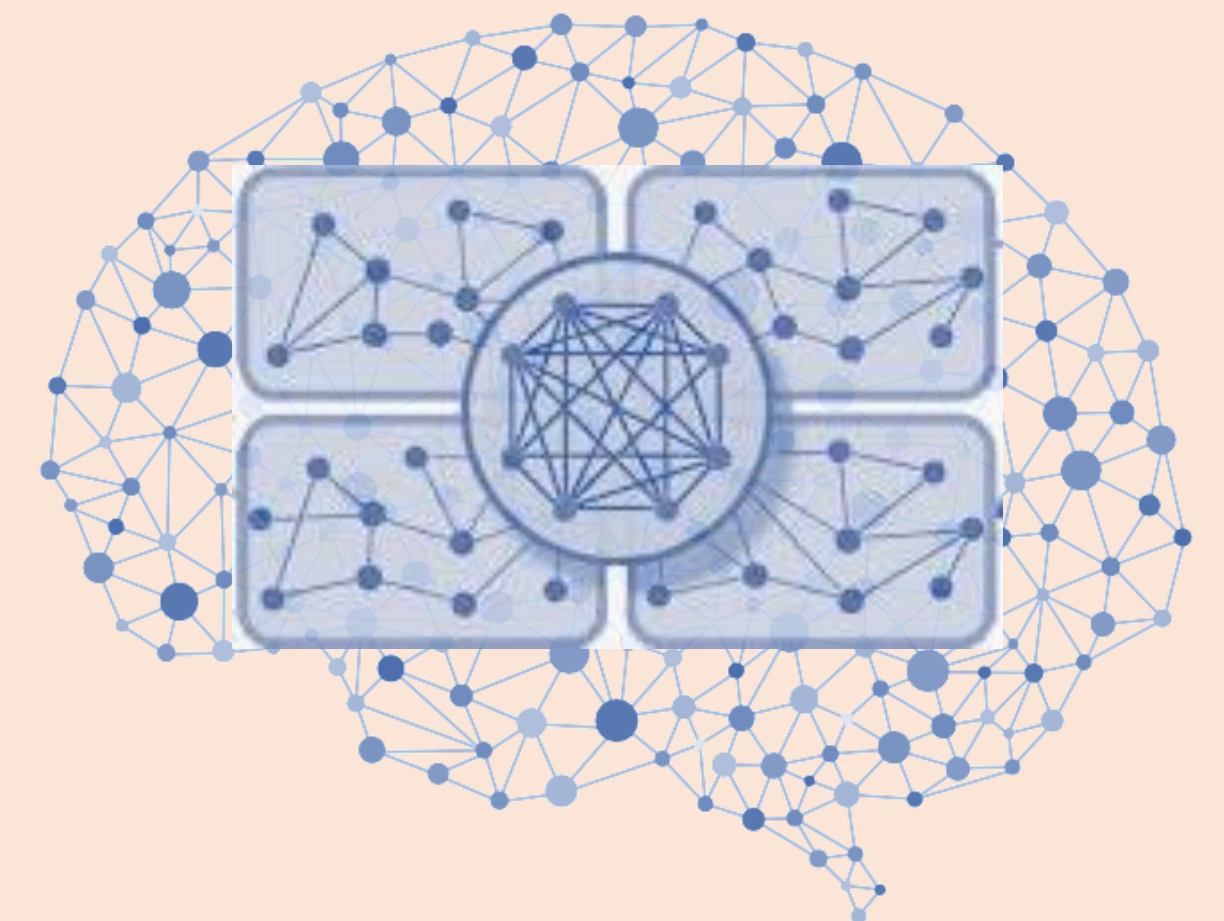
- The goal: Dataset → Architecture
- A difficult optimization problem
 - Expensive evaluations
 - A huge categorial space
- Existing solutions are biased towards current human understanding of Neural Networks structure
- Once, a game for tech-giants only



Search duration over CIFAR-10 with a single GPU.

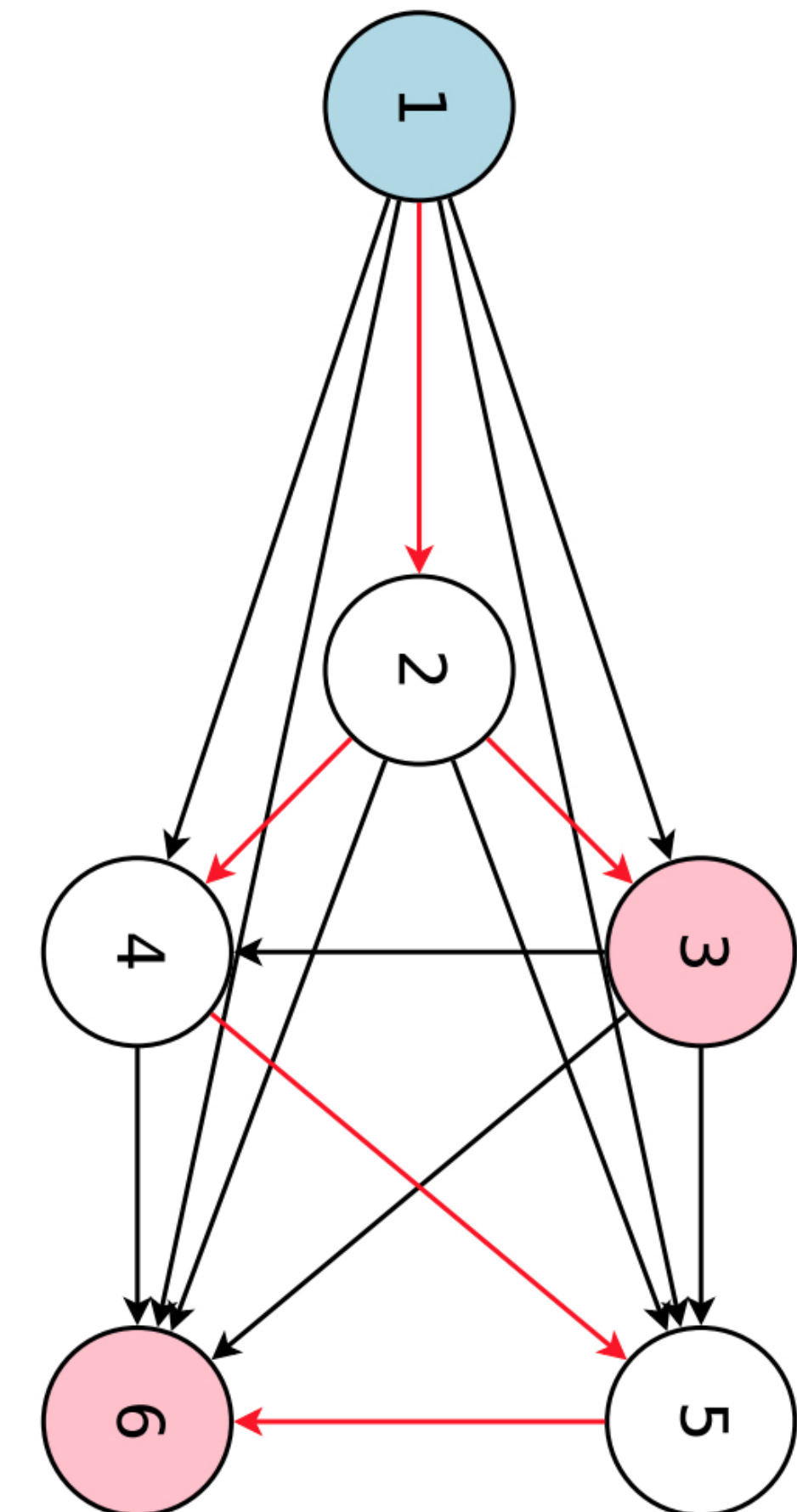
NAS

Automatic Neural
Architecture Search



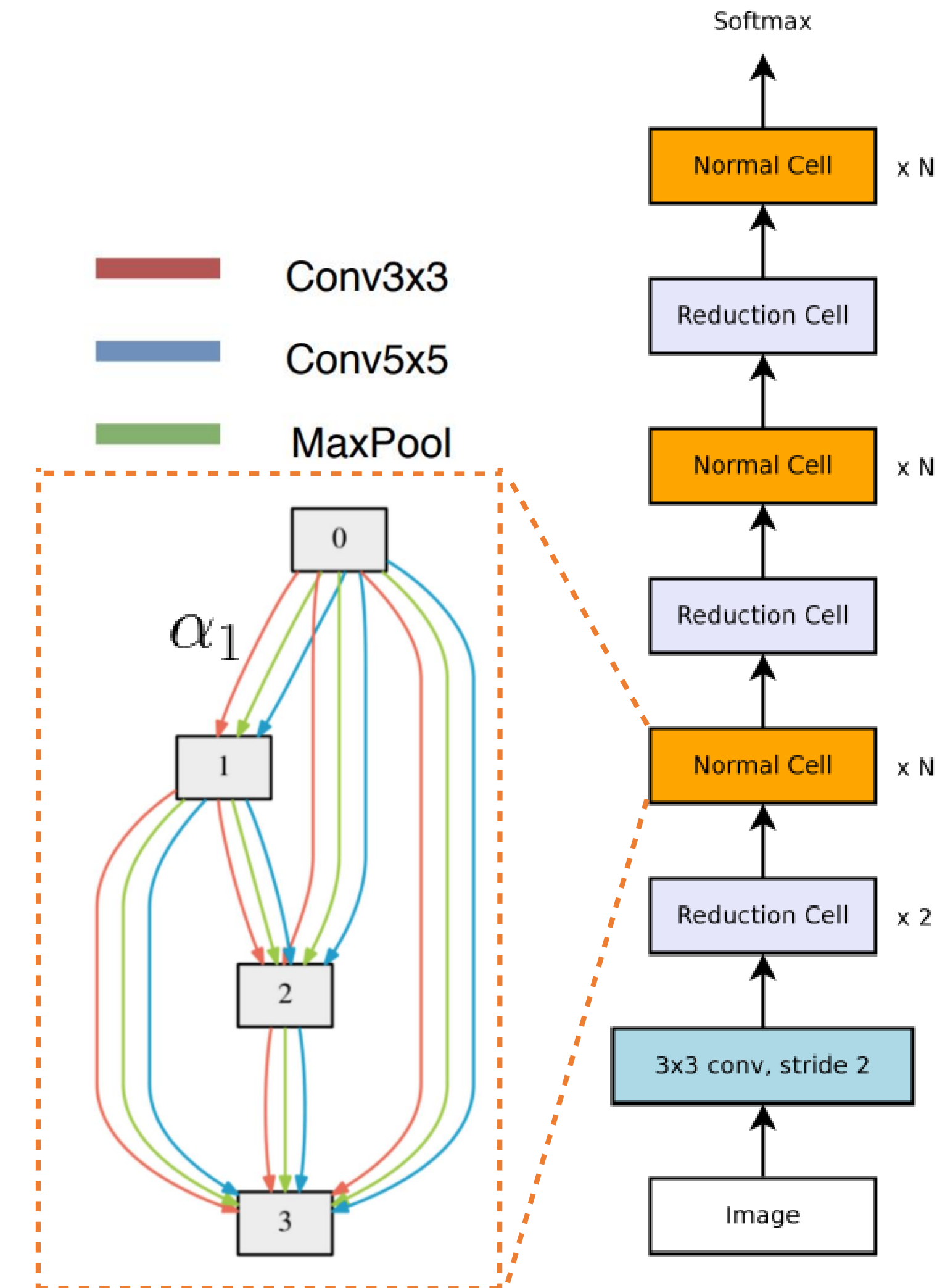
Architecture Space and Optimization

- The architectures space is represented by a super-graph
 - Nodes are features-maps (tensors)
 - Edges are operations over tensors (layers)
 - Paths are architectures
 - Space size is the number of different paths (10^{30})
- The *NAS objective*:
 - Select the path which maximizes the validation accuracy
 - Paths are sampled and scored via different techniques



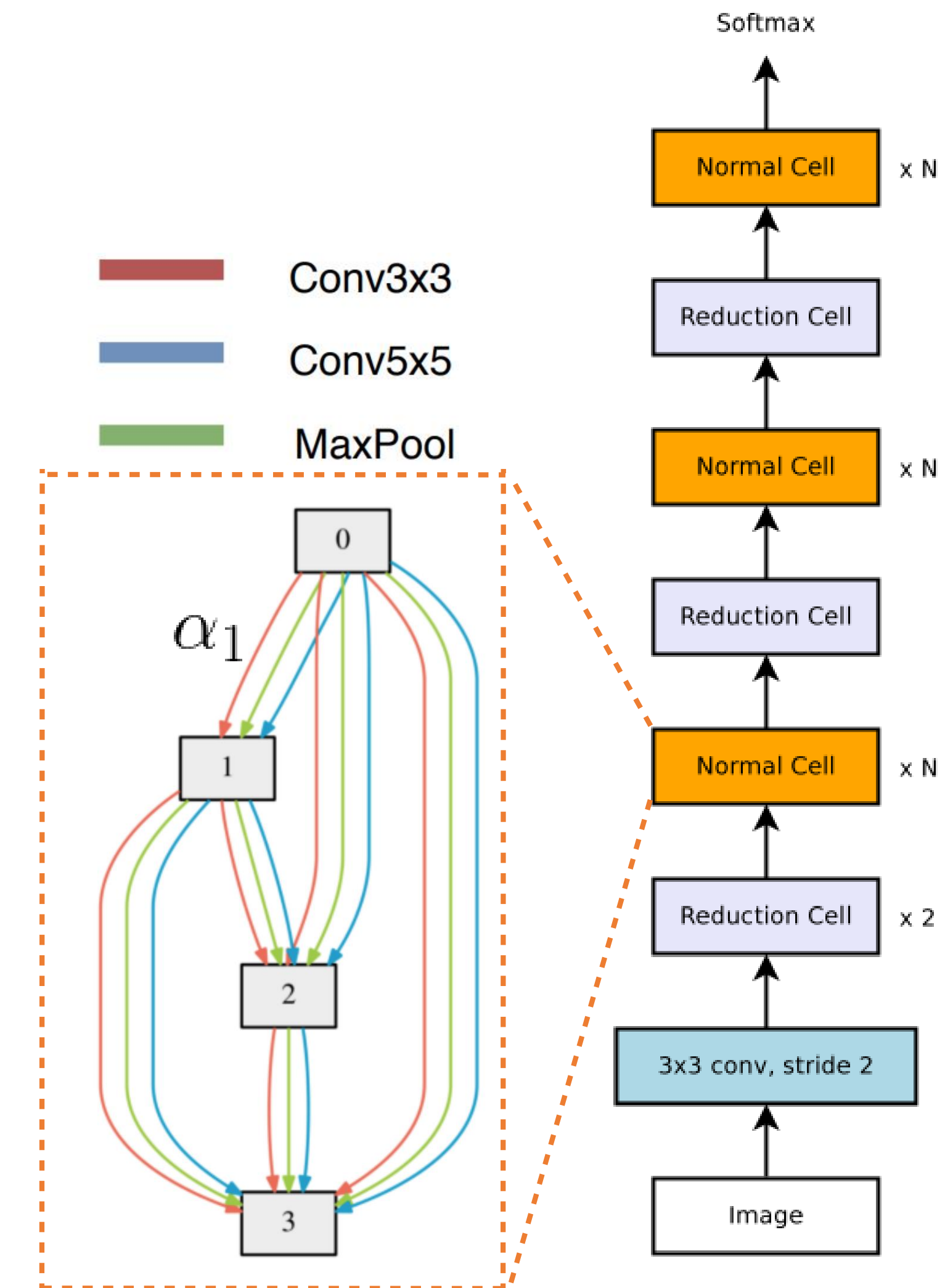
Differential Architecture Space

- The search space can be reduced to a sub-space of repetitive *cells* [NASNet, Zoph 2017]
- DARTS replaced path-sampling with super-graph training [Liu, 2018]
 - Introduced architecture-weights α
 - The sampling scheme is relaxed to *joint maximization*
 - Efficient search via gradient-descent

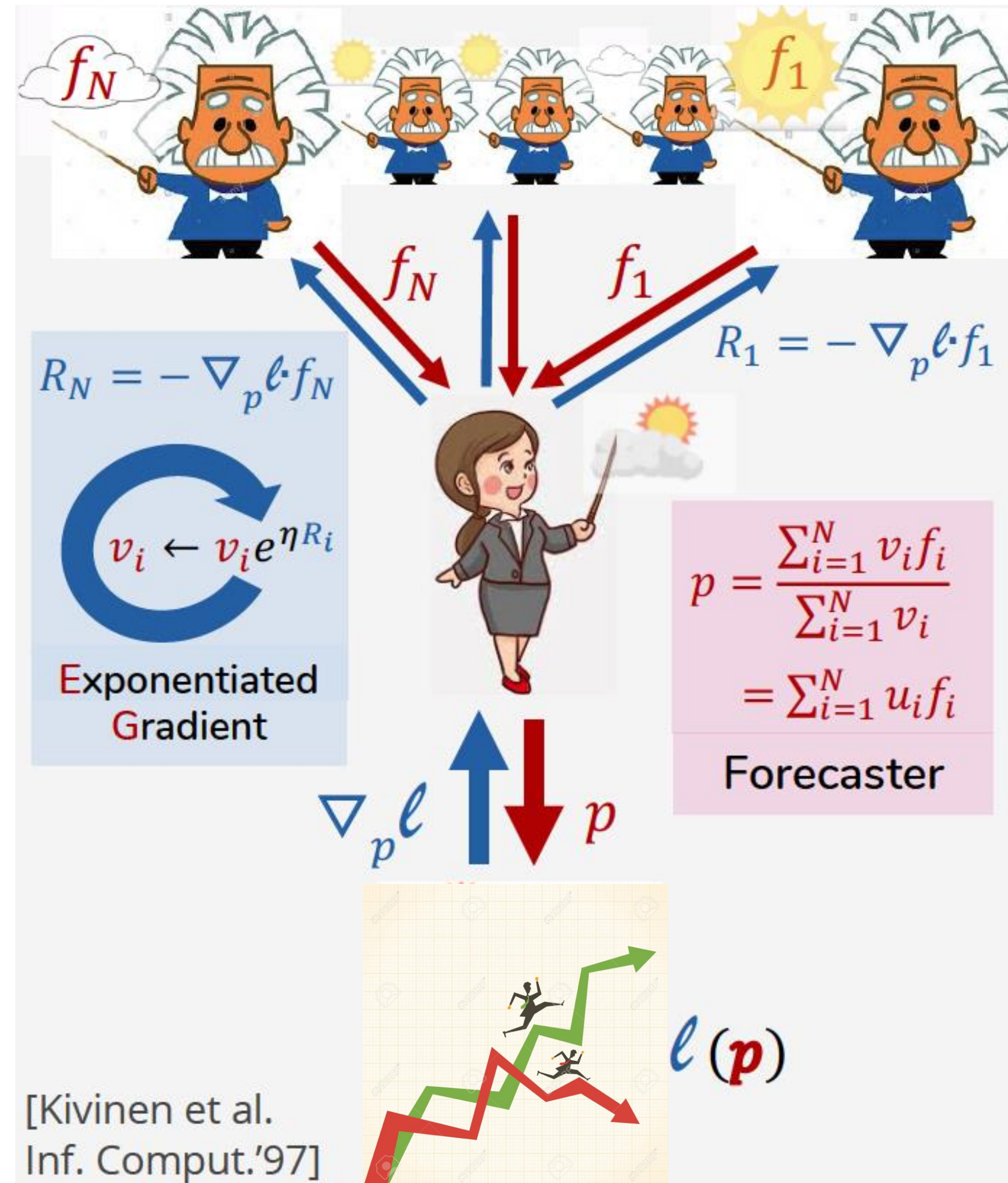


Differential Architecture Space

- DARTS Search algorithm:
 - For steps 1..T do:
 - Gradient-descent step over network weights \mathbf{w}
 - Gradient-descent step over Architecture weights α
 - Prune all operations except the best ones (largest α)
- Output architectures are practically *random* [Li, 2019]
- We argue that this optimization process is *inefficient*
 1. Start: Diverse operations \rightarrow Parameterization bias
 2. End: Harsh final pruning \rightarrow Relaxation bias
- To address that, we ask for **expert advice**



Prediction with expert advice



Prediction with expert advice

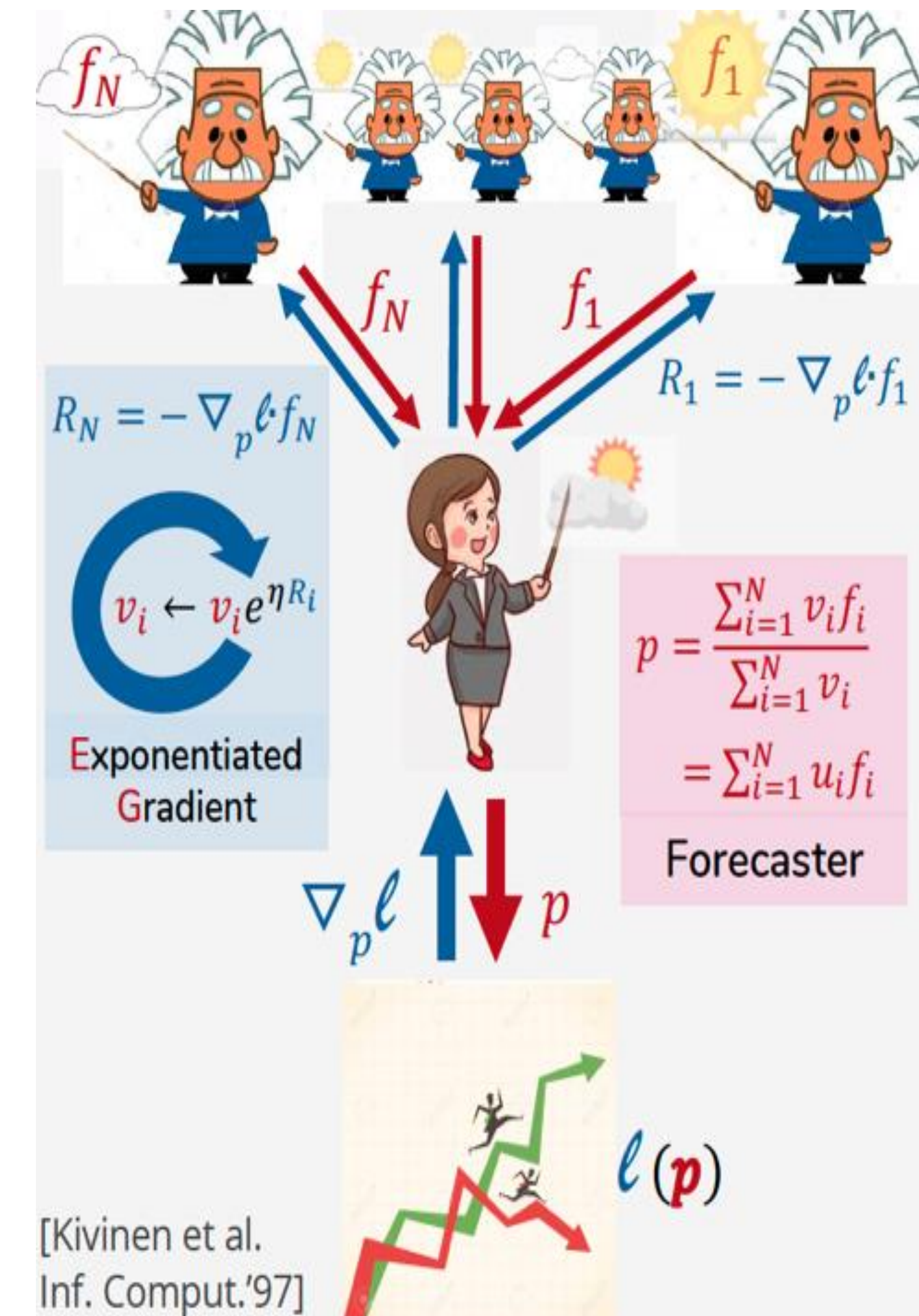
- a forecaster relies on the advice of N experts, forming an attention-vector,

$$\Delta_t = \{w \in \mathbb{R}^N : \sum_{i=1}^N w_i = 1, w \geq 0\}, \hat{h}_t = \sum_{i=1}^N w_{i,t} \hat{f}_{i,t}(x_t)$$

- Define the *accumulated regret*,

$$R_{T,N} = \sum_{t=1}^T \ell(\hat{h}_t, y_t) - \min_{i=1,\dots,n} \sum_{t=1}^T \ell_{i,t}$$

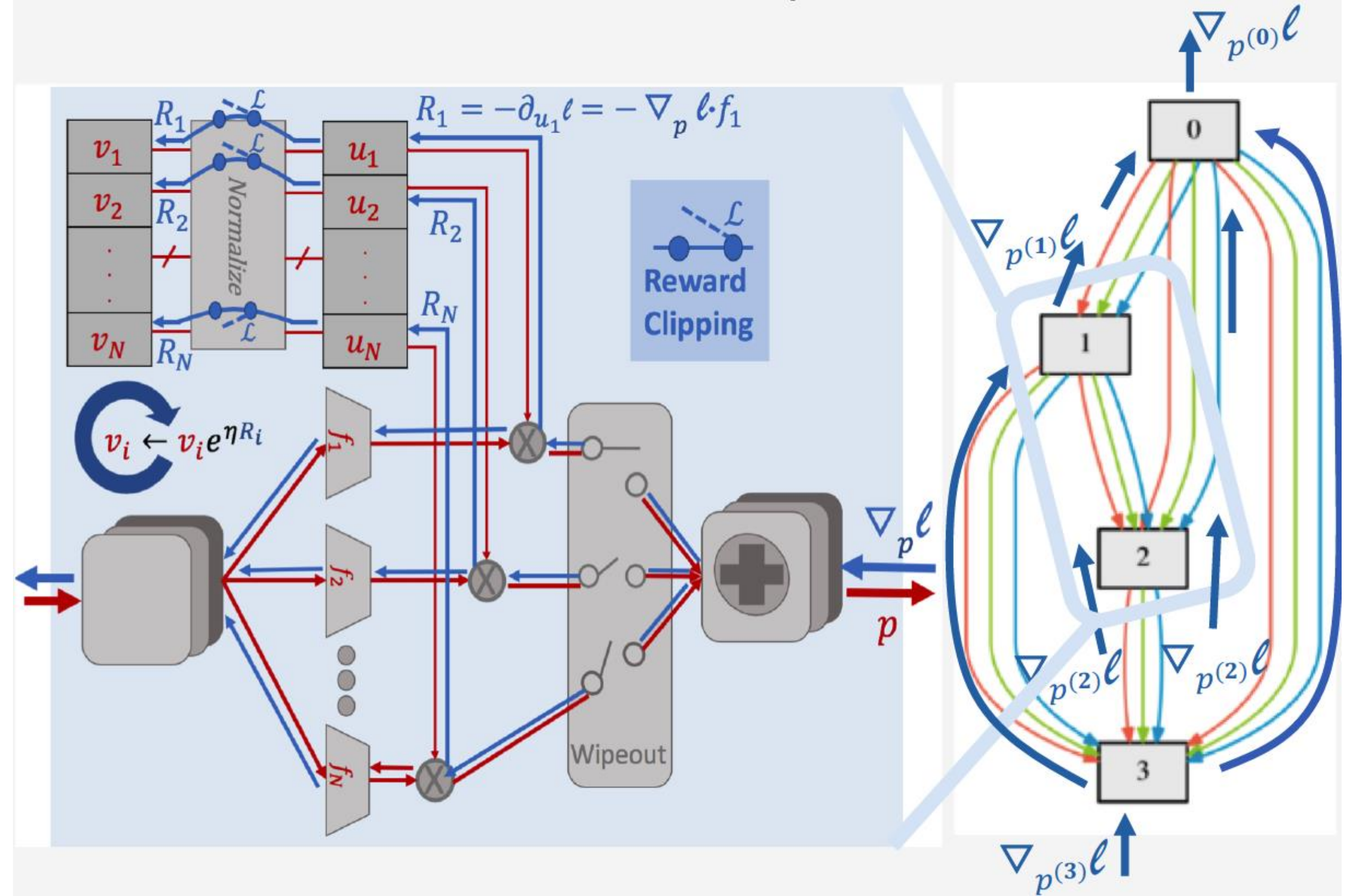
- A measure for the forecaster regret for not following best expert's advice, in hindsight
- We optimize the mixture, and select the best operation at the end
- Our experts represent **operations (layers)** and our forecaster is their **mixture tensor**



XNAS: NAS with eXpert Advice

Algorithm 1 XNAS for a single forecaster

- 1: **Input:** step size η ,
loss-gradient bound \mathcal{L} ,
Experts predictions $\{f_{t,i}\}_{i=1}^N \forall t = 1, \dots, T$
- 2: **Init:** $I_0 = \{1, \dots, N\}$, $v_{0,i} \leftarrow 1, \forall i \in I_0$
- 3: **for** rounds $t = 1, \dots, T$ **do**
- 4: Update ω by descending $\nabla_{\omega} \ell_{\text{train}}(\omega, v)$
- 5: $p_t \leftarrow \frac{\sum_{i \in I_{t-1}} v_{t-1,i} \cdot f_{t-1,i}}{\sum_{i \in I_{t-1}} v_{t-1,i}}$ #Predict
- 6: {loss gradient revealed: $\nabla_{p_t} \ell_{\text{val}}(p_t)$ }
- 7: **for** $i \in I_{t-1}$ **do**
- 8: $R_{t,i} = -\nabla_{p_t} \ell_{\text{val}}(p_t) \cdot f_{t,i}$ #Rewards
- 9: $v_{t,i} \leftarrow v_{t-1,i} \cdot \exp\{\eta R_{t,i}\}$ #EG step
- 10: **end for**
- 11: $\theta_t \leftarrow \max_{i \in I_{t-1}} \{v_{t,i}\} \cdot \exp\{-2\eta \mathcal{L}(T - t)\}$
- 12: $I_t \leftarrow I_{t-1} \setminus \{i \mid v_{t,i} < \theta_t\}$ #Wipeout
- 13: **end for**



XNAS: Wipeout

- Wipeout is a *safe* procedure,

Lemma 1. *In XNAS, the optimal expert in hindsight cannot be wiped-out.*

- *Advantages* of dynamic wipeout of inferior operations,

1. Speeds up the search
2. Decreases the network's complexity
3. Mitigates the relaxation bias

Algorithm 1 XNAS for a single forecaster

```
1: Input: step size  $\eta$ ,  
   loss-gradient bound  $\mathcal{L}$ ,  
   Experts predictions  $\{f_{t,i}\}_{i=1}^N \forall t = 1, \dots, T$   
2: Init:  $I_0 = \{1, \dots, N\}$ ,  $v_{0,i} \leftarrow 1, \forall i \in I_0$   
3: for rounds  $t = 1, \dots, T$  do  
4:   Update  $\omega$  by descending  $\nabla_{\omega} \ell_{\text{train}}(\omega, v)$   
5:    $p_t \leftarrow \frac{\sum_{i \in I_{t-1}} v_{t-1,i} \cdot f_{t-1,i}}{\sum_{i \in I_{t-1}} v_{t-1,i}}$  #Predict  
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7:   for  $i \in I_{t-1}$  do  
8:      $R_{t,i} = -\nabla_{p_t} \ell_{\text{val}}(p_t) \cdot f_{t,i}$  #Rewards  
9:      $v_{t,i} \leftarrow v_{t-1,i} \cdot \exp \{\eta R_{t,i}\}$  #EG step  
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12:   $I_t \leftarrow I_{t-1} \setminus \{i \mid v_{t,i} < \theta_t\}$  #Wipeout  
13: end for
```


XNAS: Theoretical guarantees

- The *aggregated wipeout factor* measures the extent of the wipeout,

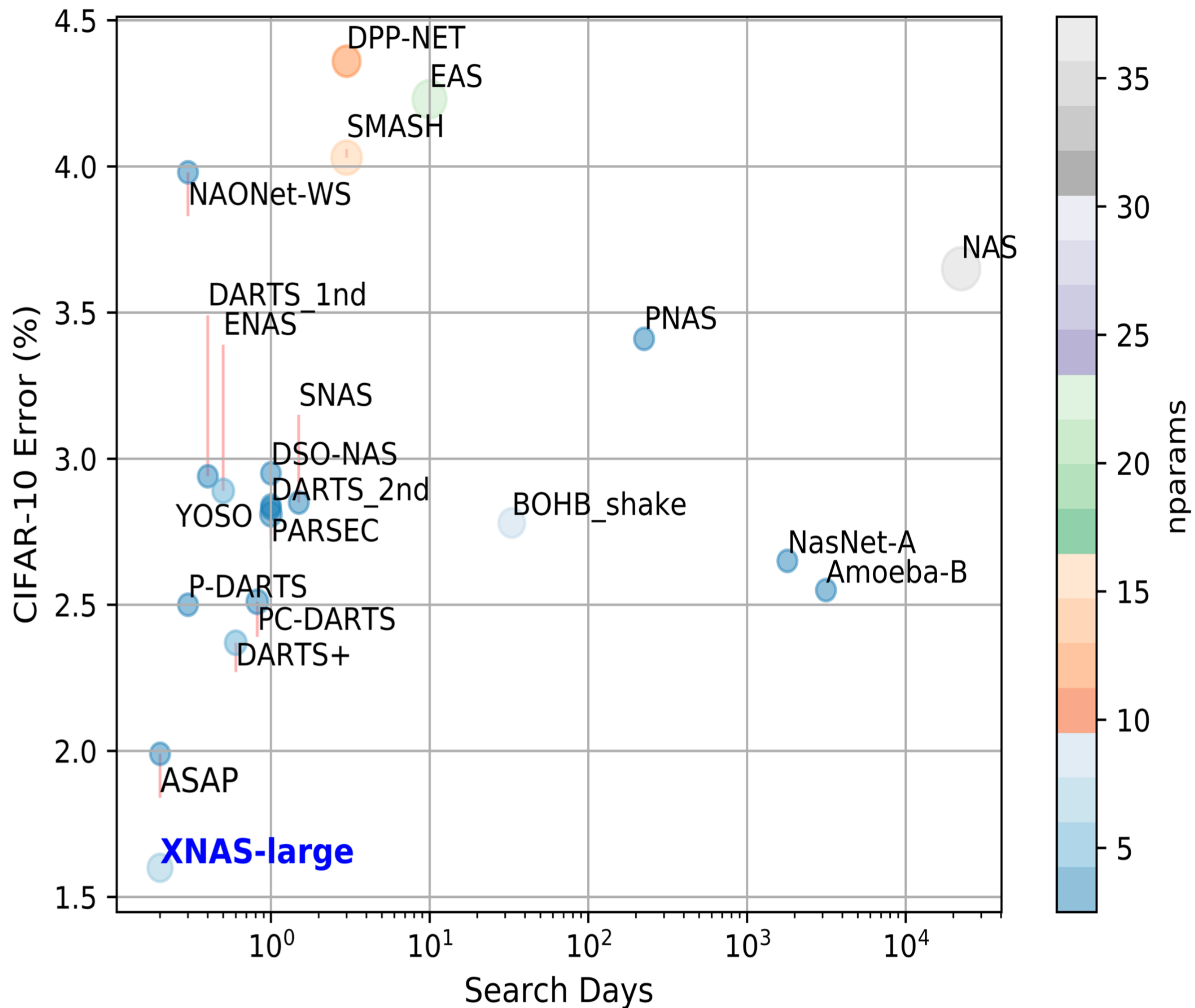
$$\gamma_t := \prod_{t=1}^T \frac{\sum_{i \in I_{t-1}} v_{t,i}}{\sum_{i \in I_t} v_{t,i}}$$

- Tight worst-case regret upper-bound is achieved,

Theorem 1 (XNAS Regret Bound). *The regret of the XNAS algorithm 1, with N experts and learning rate η , incurring a sequence of T non-negative convex losses of \mathcal{L} -bounded rewards, satisfies,*

$$\eta^* = \sqrt{\frac{2 \ln N}{T \mathcal{L}^2}} \quad ; \quad \text{Regret}_T \leq \mathcal{L} \sqrt{2T \ln N} \left(1 - \frac{1}{2} \frac{\ln \gamma_T}{\ln N} \right) \quad (3)$$

Results: CIFAR-10



Results

- Public datasets:

Datasets Architecture	CIFAR100 Error	FMNIST Error	SVHN Error	Freiburg Error	CINIC10 Error	ImageNet Error	Search cost
Known SotA	10.7 (3)	3.65 (24)	1.02 (3)	10.7 (14)	6.83 (14)	15.6 (6)	-
SNAS (22)	16.5	3.72	1.98	14.7	7.13	27.3	1.5
PNAS (10)	15.9	3.72	1.83	12.3	7.03	25.8	150
Amoeba-A (16)	15.9	3.8	1.93	11.8	7.18	25.5	3150
NASNet (25)	15.8	3.71	1.96	13.4	6.93	26.0	1800
DARTS (11)	15.7	3.68	1.95	10.8	6.88	26.7	1
ASAP (14)	15.6	3.71	1.81	10.7	6.83	26.7	0.2
XNAS	13.6	3.64	1.72	6.3	6.0	23.9	0.3

- Internal Alibaba datasets:

- Competitive results with tailor-made models in several tasks
- State-of-the-art results with '**AliExpress**' : **1,000,000 classes, 86% accuracy!**

Thanks!

Have a computer vision task?

Give us data and get predictions (for free)

Want to know more about AutoML?

Stay tuned for future events by **MIIL**

Interested at what we do?

Let's get in touch: **Asaf.noy@alibaba-inc.com**