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Towards Computer Vision as a Service

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DAMO

Discovery, Adventure, Momentum and Outlook

MIT

Machine Intelligence Technology

IMVL

Israel Machine Vision Lab

Machine Intelligence

- 壹 Speech Lab
- 贰 Vision Lab
- 叁 Language Technology Lab
- 肆 Decision Intelligence Lab
- 伍 City Brain Lab

The Alibaba Damo machine intelligence is devoted to research and application in cutting-edge machine intelligence, provides the...

Data Computing

DAMO Research

Robotics

DAMO Research

Financial Technology

DAMO Research

X Laboratory

DAMO Research

https://damo.alibaba.com

AutoML Main Goal

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AI is still beyond reach to most companies & people

Even tech-giants are struggling to answer the need in new fields

AI Experts are busy tuning parameters

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AutoML::Classification

Upload your data

AutoML

State-of-the-Art Model

+

Statistics

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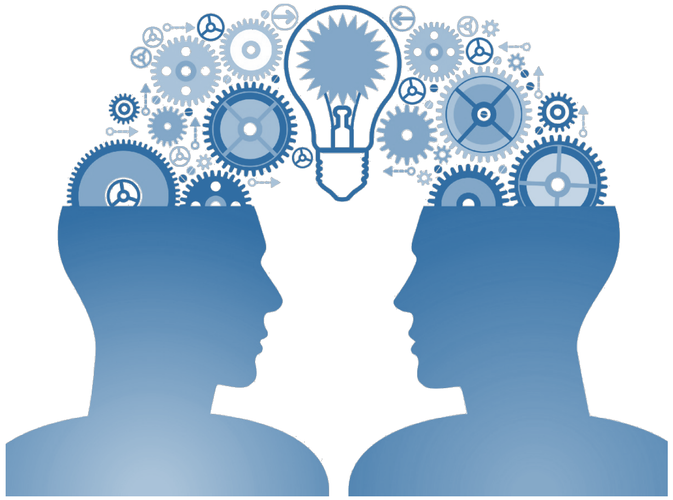
AutoML for NN: Main directions

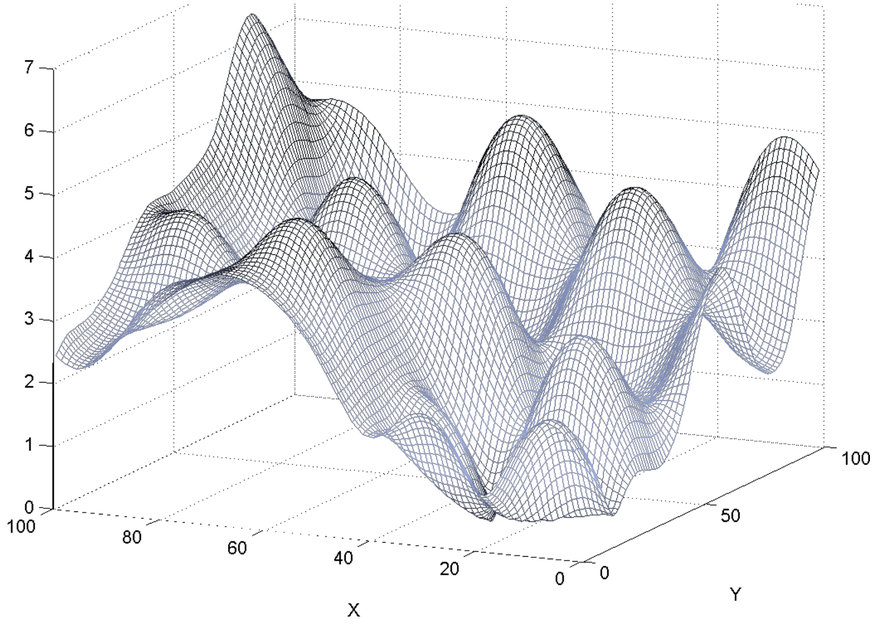
TL

Transfer **L**earning/knowledge between similar tasks



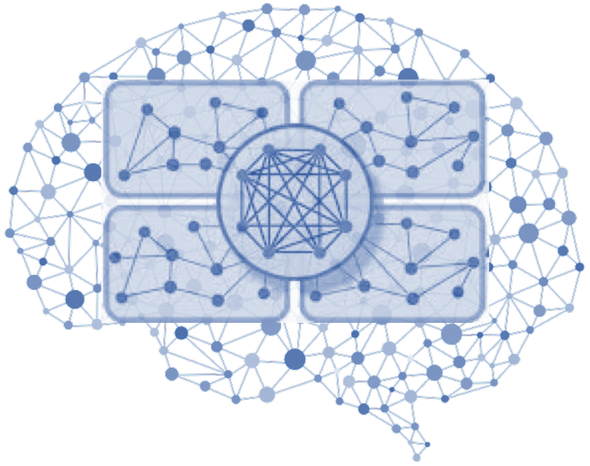
HPO

Automatic **H**yper-**P**arameter **O**ptimization



NAS

Automatic **N**eural **A**rchitecture **S**earch



AutoML for NN: Main directions

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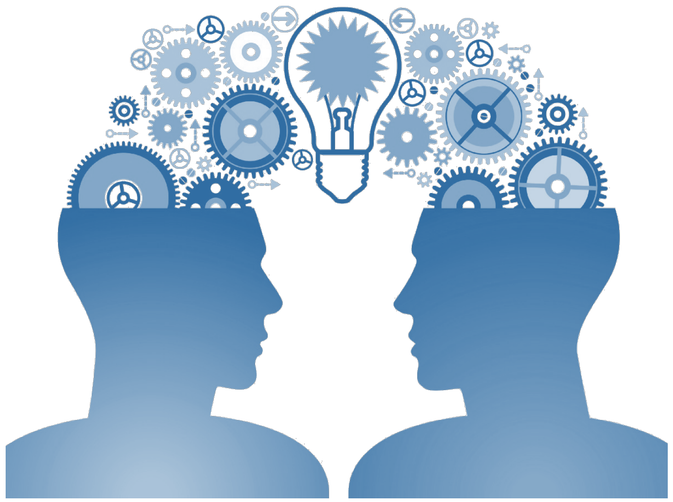
TL

Transfer **L**earning/knowledge between similar tasks



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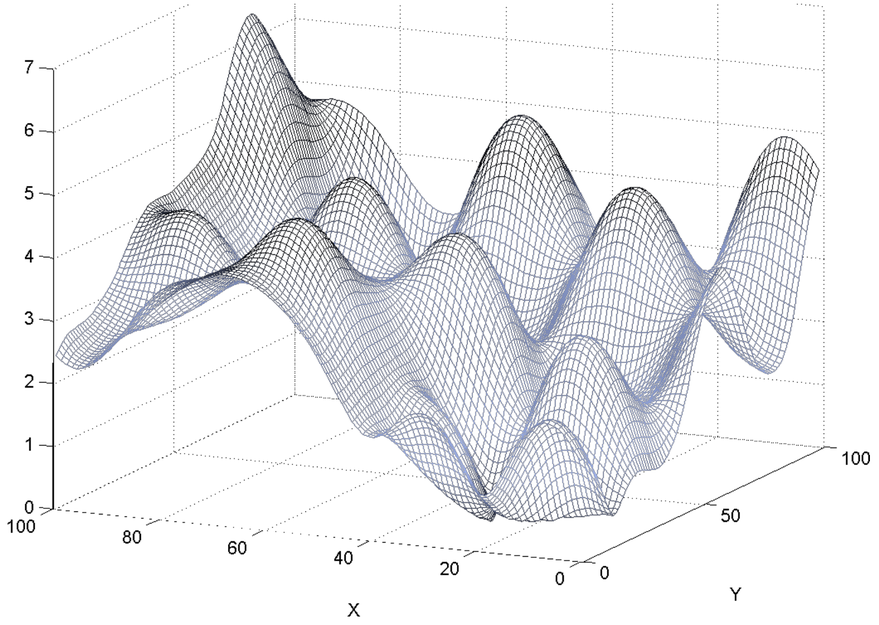

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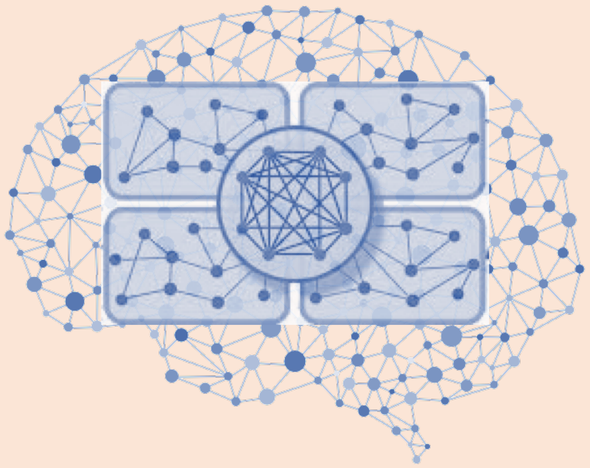

NAS Overview

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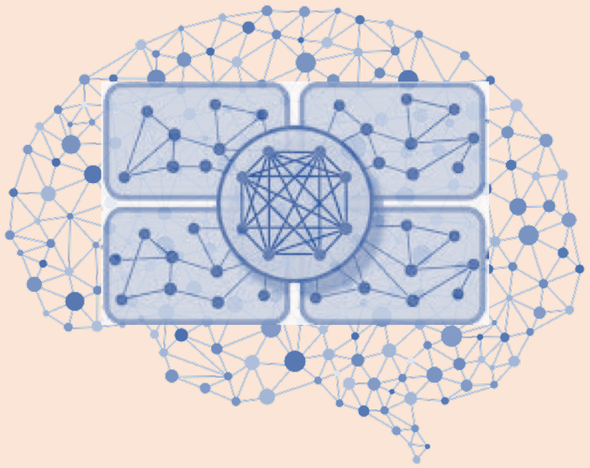
- The success of deep learning in perceptual tasks is largely due to its automation of the feature engineering process
- This success led to a rising demand for architecture engineering
- NAS, architecture engineering automation, is a logical next step in the mission of fully automating machine learning

NAS

Automatic **N**eural **A**rchitecture **S**earch



NAS Overview

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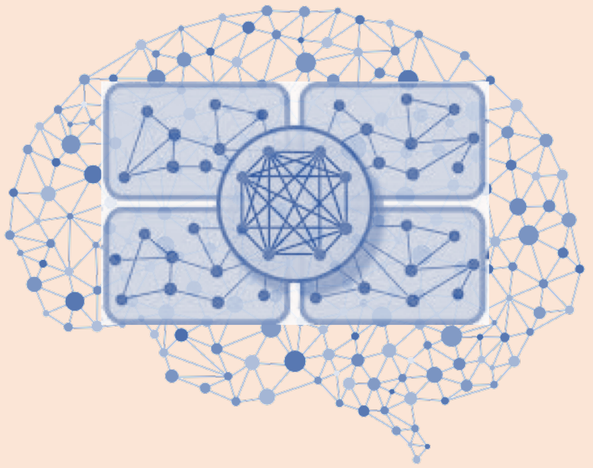
- The goal: Dataset → Architecture
- A difficult optimization problem
  - Expensive evaluations
  - A huge categorial space
- Existing solutions are biased towards current human understanding of Neural Networks structure
- Once, a game for tech-giants only

NAS

Automatic **N**eural **A**rchitecture **S**earch



NAS [Zoph] 22,000 days — 2016

AmoebaNet [Liu] 3,150 days — 2017

DARTS [Liu] 1 day — 2018

XNAS/ASAP [ours] 4-6 hours — 2019

Search duration over CIFAR-10 with a single GPU.

Architecture Space and Optimization

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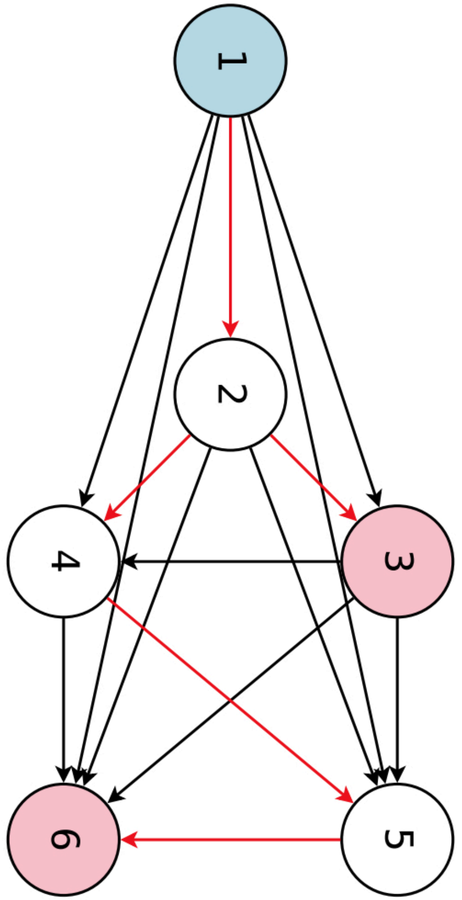
- The architectures space is represented by a super-graph
  - Nodes are features-maps (tensors)
  - Edges are operations over tensors (layers)
  - Paths are architectures
  - Space size is the number of different paths (10^{30})

- The *NAS objective*:
  - Select the path which maximizes the validation accuracy
    - Paths are sampled and scored via different techniques



Differential Architecture Space

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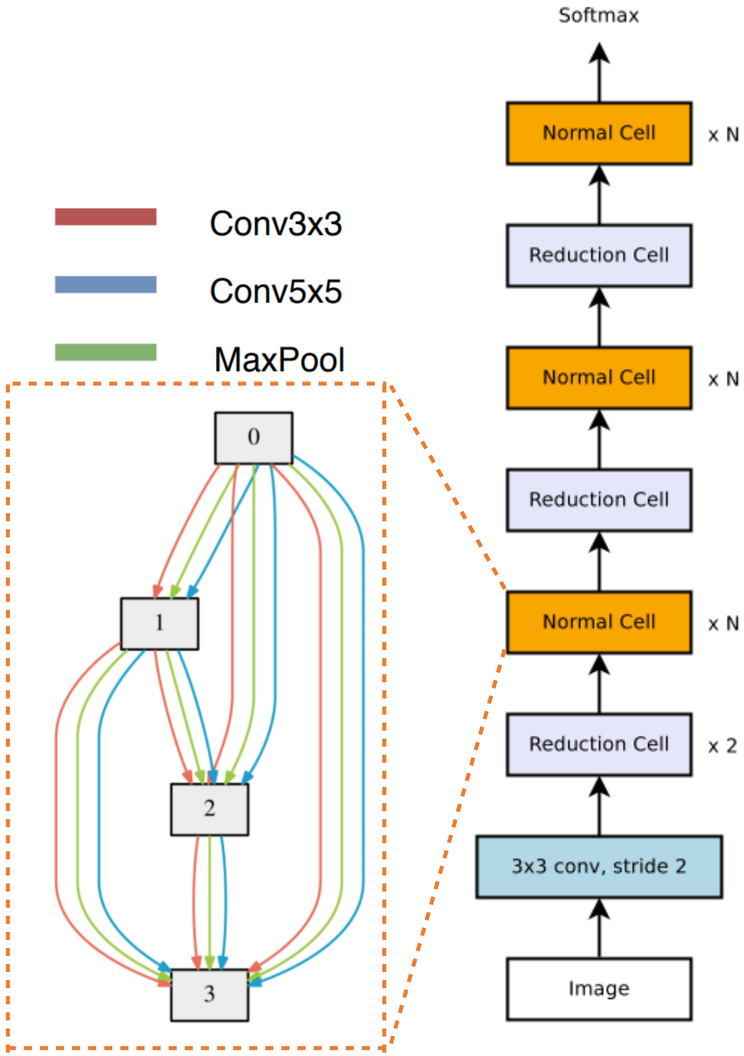
- The search space can be reduced to a sub-space of repetitive *cells* [NASNet, Zoph 2017]
- DARTS replaced path-sampling with super-graph training [Liu, 2018]
  - Introduced architecture-weights α
  - The sampling scheme is relaxed to *joint maximization*
  - Efficient search via gradient-descent



Differential Architecture Space

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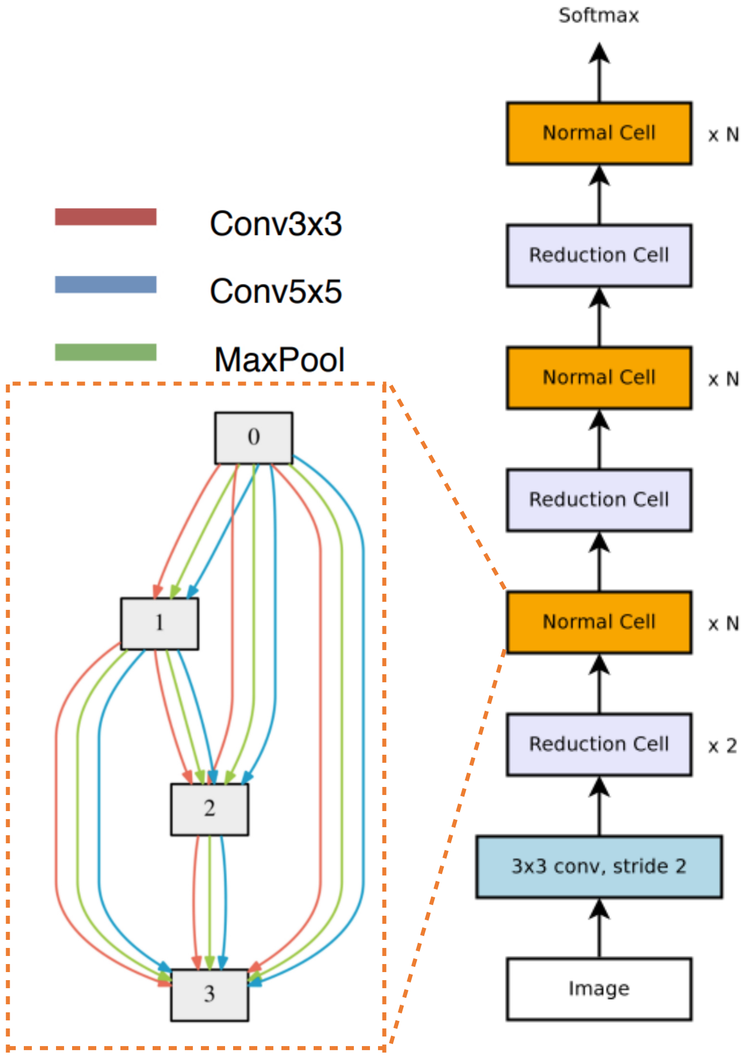
- DARTS Search algorithm:
  - For steps 1..T do:
    - Gradient-descent step over network weights **w**
    - Gradient-descent step over Architecture weights **α**
  - Prune all operations except the best ones (largest **α**)
- Output architectures are practically *random [Li, 2019]*
- We argue that this optimization process is *inefficient*
  1. Diverse operations → Parameterization bias
  2. Harsh final pruning → Relaxation bias
- To address that, we ask for an ***expert advice***



Prediction with expert advice

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- The expert advice setup is motivated by *online optimization* tasks,
  as playing repeated games, compressing data or trading stocks
- The forecaster relies on the advice of N experts, forming an attention-vector,

$$\Delta_t = \{\boldsymbol{w} \in \mathbb{R}^N : \sum_{i=1}^{N} \boldsymbol{w}_i = 1,\ \boldsymbol{w} \geq 0\}\ ,\ \hat{h}_t = \sum_{i=1}^{N} \boldsymbol{w}_{i,t} \hat{f}_{i,t}(\boldsymbol{x}_t)$$

  - Our experts represent **operations** and our forecaster is their **mixture tensor**

- Define the *accumulated regret*,

$$R_{T,N} = \sum_{t=1}^{T} \ell(\hat{h}_t, y_t) - \min_{i=1,..,n} \sum_{t=1}^{T} \ell_{i,t}$$

  - A measure for the forecaster regret for not following best expert's advice, in hindsight
  - We optimize a mixture of experts and select the best expert at the end

XNAS: NAS with eXpert Advice

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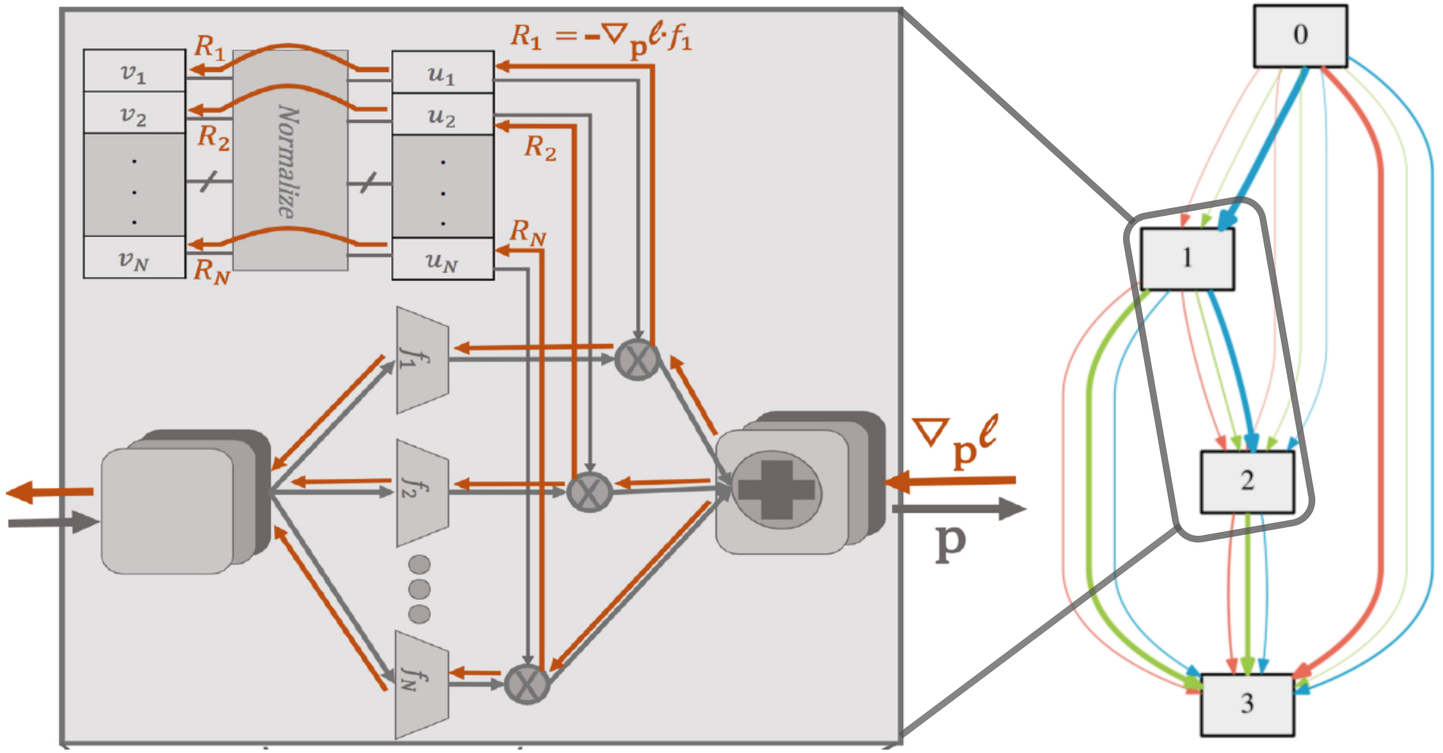
Algorithm 1 XNAS for a single forecaster

Input: step size η,
loss-gradient bound $\mathcal{L}$,
Experts predictions $\{f_{t,i}\}_{i=1}^{N} \ \forall t = 1, \ldots, T$
Init: $I_0 = \{1, \ldots, N\}$, $v_{0,i} \leftarrow 1, \ \forall i \in I_0$
for rounds $t = 1, \ldots, T$ **do**
  Update $\boldsymbol{\omega}$ by descending $\nabla_{\boldsymbol{\omega}} \ell_{\text{train}}(\boldsymbol{\omega}, \boldsymbol{v})$
  $p_t \leftarrow \dfrac{\sum_{i \in I_{t-1}} v_{t-1,i} \cdot f_{t-1,i}}{\sum_{i \in I_{t-1}} v_{t-1,i}}$ #Predict
  {loss gradient revealed: $\nabla_{p_t} \ell_{\text{val}}(p_t)$}
  for $i \in I_{t-1}$ **do**
    $R_{t,i} = -\nabla_{p_t} \ell_{\text{val}}(p_t) \cdot f_{t,i}$ #Rewards
    $v_{t,i} \leftarrow v_{t-1,i} \cdot \exp\{\eta R_{t,i}\}$ #EG step
  end for
  $\theta_t \leftarrow \max_{i \in I_{t-1}} \{v_{t,i}\} \cdot \exp\{-2\eta \mathcal{L}(T-t)\}$
  $I_t \leftarrow I_{t-1} \setminus \{i \mid v_{t,i} < \theta_t\}$ #Wipeout
end for



XNAS: Wipeout

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- Dynamic wipe out of inferior operations
  1. Speeds up the search
  2. Decreases the network's complexity
  3. Mitigates the relaxation bias

- It is a *safe* procedure,

Lemma 1. *In XNAS, the optimal expert in hindsight cannot be wiped-out.*

Algorithm 1 XNAS for a single forecaster

Input: step size η,
loss-gradient bound $\mathcal{L}$,
Experts predictions $\{f_{t,i}\}_{i=1}^{N} \ \forall t = 1, \ldots, T$
Init: $I_0 = \{1, \ldots, N\}, \ v_{0,i} \leftarrow 1, \ \forall i \in I_0$
for rounds $t = 1, \ldots, T$ **do**
  Update $\boldsymbol{\omega}$ by descending $\nabla_{\boldsymbol{\omega}} \ell_{\text{train}}(\boldsymbol{\omega}, \boldsymbol{v})$
  $p_t \leftarrow \frac{\sum_{i \in I_{t-1}} v_{t-1,i} \cdot f_{t-1,i}}{\sum_{i \in I_{t-1}} v_{t-1,i}}$ #Predict
  {loss gradient revealed: $\nabla_{p_t} \ell_{\text{val}}(p_t)$}
  for $i \in I_{t-1}$ **do**
    $R_{t,i} = -\nabla_{p_t} \ell_{\text{val}}(p_t) \cdot f_{t,i}$ #Rewards
    $v_{t,i} \leftarrow v_{t-1,i} \cdot \exp\{\eta R_{t,i}\}$ #EG step
  end for
  $\theta_t \leftarrow \max_{i \in I_{t-1}} \{v_{t,i}\} \cdot \exp\{-2\eta \mathcal{L}(T-t)\}$
  $I_t \leftarrow I_{t-1} \setminus \{i \mid v_{t,i} < \theta_t\}$ #Wipeout
end for

XNAS: Theoretical guarantees

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- The *aggregated wipeout factor measures the extent of the wipeout,*

$$\gamma_t := \prod_{t=1}^{T} \frac{\sum_{i \in I_{t-1}} v_{t,i}}{\sum_{i \in I_t} v_{t,i}}$$

- Tight worst-case regret upper-bound is achieved,

Theorem 1 (XNAS Regret Bound)**.** *The regret of the XNAS algorithm 1, with N experts and learning rate η, incurring a sequence of T non-negative convex losses of $\mathcal{L}$-bounded rewards, satisfies,*

$$\eta^* = \sqrt{\frac{2 \ln N}{T \mathcal{L}^2}} \quad ; \quad \text{Regret}_T \leq \mathcal{L} \sqrt{2T \ln N} \left(1 - \frac{1}{2} \frac{\ln \gamma_T}{\ln N}\right) \tag{3}$$

- Arxiv preprint will be soon available:

XNAS: Neural Architecture Search with Expert Advice

ASAP – The Fastest NAS

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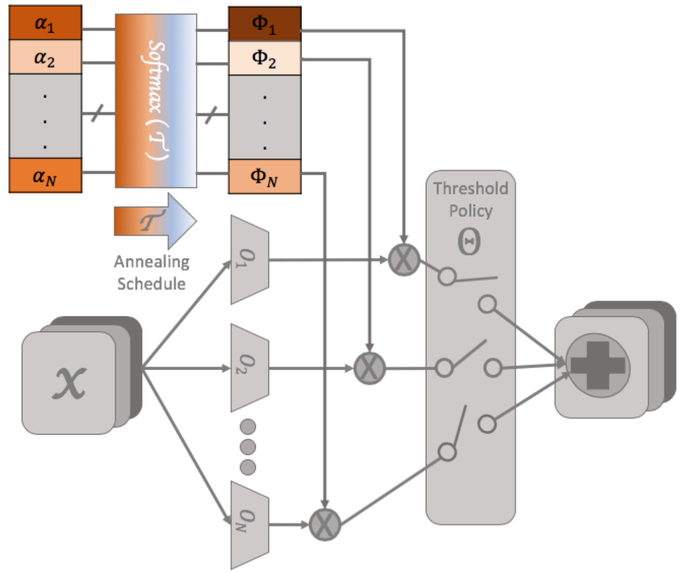
- *XNAS* plans for the worst

- *ASAP* offers control over operations pruning-rate via *temperature-annealing*
- *The annealing schedule* can depend on the dataset or costumer needs
- Theoretical guarantees are provided under statistical assumptions

- Arxiv preprint:

  ASAP: Architecture Search, Anneal and Prune.

  arXiv preprint arXiv:1904.04123



Algorithm 1 ASAP for a single Mixed Operation

Input: Operations $o_i \in \mathcal{O}$ $i \in \{1, .., N\}$,
Annealing schedule $\mathcal{T}$,
Grace-temperature τ,
Threshold policy Θ,
Init: $T \leftarrow \mathcal{T}(0), \theta \leftarrow \Theta(0)$ $\boldsymbol{\alpha}_i \leftarrow 0$ $i \in \{1, .., N\}$.
while $|\mathcal{O}| > 1$ **do**
  Update $\boldsymbol{\omega}$ by descend step over $\nabla_{\boldsymbol{\omega}} \mathcal{L}_{\text{train}}(\boldsymbol{\omega}, \boldsymbol{\alpha}; T)$
  if $T < \tau$ **then**
    Update $\boldsymbol{\alpha}$ by descend step over $\nabla_{\boldsymbol{\alpha}} \mathcal{L}_{\text{val}}(\boldsymbol{\omega}, \boldsymbol{\alpha}; T)$
    for each $o_i \in \mathcal{O}$ such that $\Phi_{o_i}(\boldsymbol{\alpha}; T) < \theta$ **do**
      $\mathcal{O} = \mathcal{O} \setminus \{o_i\}$
    end for
  end if
  Update T according to $\mathcal{T}$
  Update θ according to Θ
end while
return $\mathcal{O}$

Results: CIFAR-10

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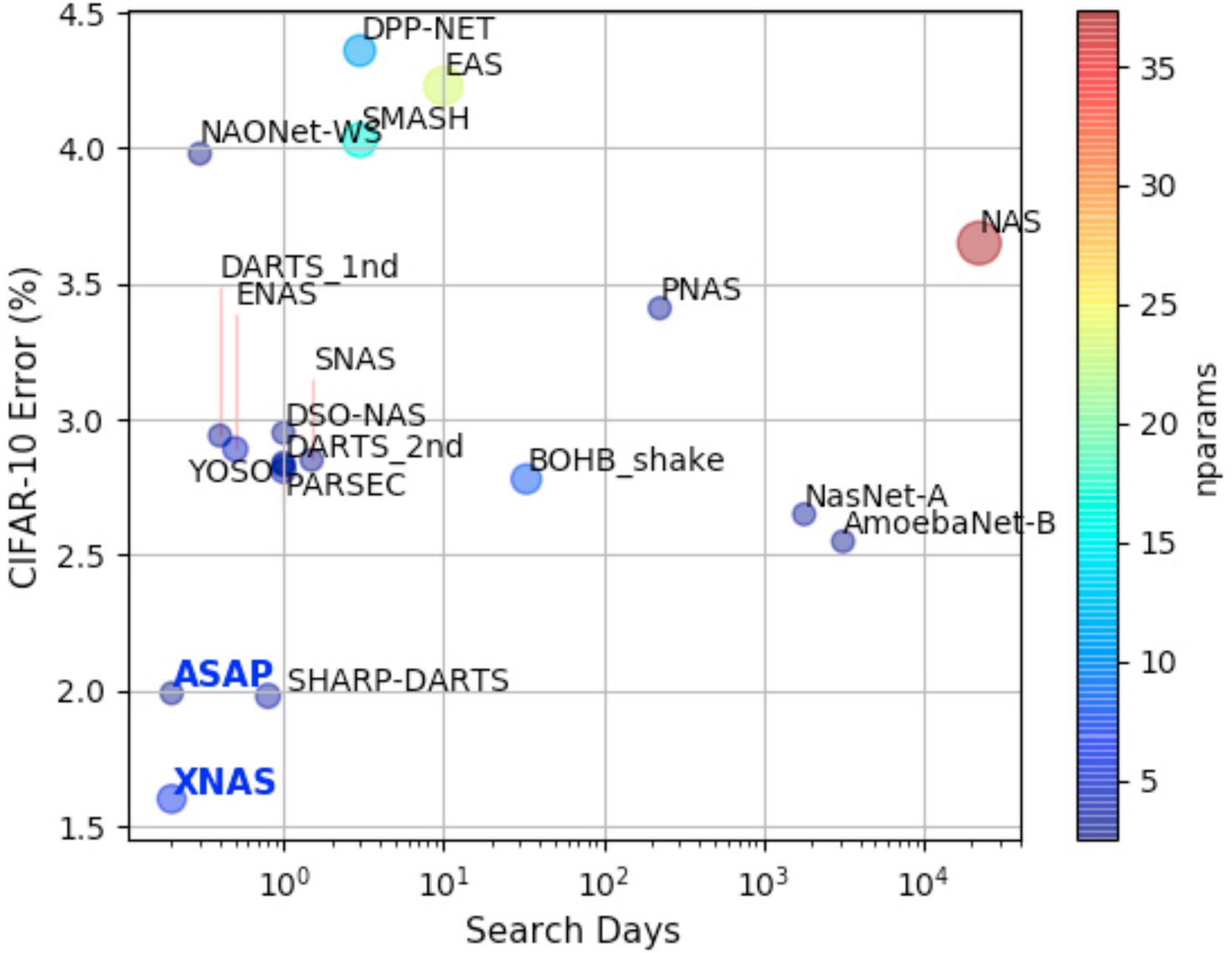

Results: various datasets

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Datasets Architecture	CIFAR100 Error	FMNIST Error	SVHN Error	Freiburg Error	CINIC10 Error	ImageNet Error	Search cost
Known SotA	**10.7** (3)	3.65 (24)	**1.02** (3)	10.7 (14)	6.83 (14)	15.7 (6)	-
SNAS (22)	16.5	3.72	1.98	14.7	7.13	27.3	1.5
PNAS (10)	15.9	3.72	1.83	12.3	7.03	25.8	150
Amoeba-A (16)	15.9	3.8	1.93	11.8	7.18	25.5	3150
NASNet (25)	15.8	3.71	1.96	13.4	6.93	26.0	1800
DARTS (11)	15.7	3.68	1.95	10.8	6.88	26.7	1
ASAP (14)	15.6	3.71	1.81	10.7	6.83	26.7	0.2
XNAS	13.6	**3.64**	1.72	**6.3**	**6.0**	24.2	0.3

- Alibaba internal datasets:

  Competitive results with tailor-made models, with up to ***1,000,000 classes***

Thanks!

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Have a computer vision task?	Give us data and get predictions
Want to know more about AutoML?	AutoML-meetup at our office next week (11.6)
Interested at what we do?	Let’s get in touch: **Asaf.noy@alibaba-inc.com**